

Mar 21, 2025

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RESEARCH INTEREST

My research interests span the area of 3D computer vision, with strong connections to robotics, graphics, and computational photography. In particular, I am interested in developing automatic localization/positioning and mapping algorithms/systems for visual images/videos and their applications to real-world practice.

EDUCATION

ETH Zurich, Department of Computer Science <i>PhD student in Computer Science, Advised by Prof. Marc Pollefeys</i>	Oct 2022 – Present
ETH Zurich, Department of Computer Science <i>Master's in computer science</i>	Sep 2020 – Sep 2022
Tsinghua University, Department of Electronic Engineering <i>Bachelor of Engineering in Electronic Engineering</i> Top 10% (GPA: 3.75/4.0)	Aug 2015 – Jun 2020

EXPERIENCE

Google – Zurich, Switzerland <i>[Student Researcher] Visual Mapping Group at Google Geo.</i> • Topic: Quantizing / Tokenizing 3D Neural Maps for Memory-Efficient Visual Localization.	Jul 2024 – Dec 2024
ByteDance Inc. – Beijing, China <i>[Research Intern] Group "SLAM & 3D Vision".</i> • Topic: plane-assisted multi-view stereo, multiple plane detection, segmentation, and estimation for daily videos. [7] [8]	Jan 2020 – Sep 2021
ETH Zurich - Zurich, Switzerland <i>[Academic Guest] Computer Vision and Geometry Group (CVG). Led by Prof. Marc Pollefeys.</i> • Topic: 3D reconstruction (structure-from-motion, differentiable rendering) [5]	Jul 2019 – Nov 2019
Microsoft Research Asia - Beijing, China <i>[Research Intern] Visual Computing Group.</i> • Topic: Deep learning for Object recognition, detection and segmentation. [3]	Dec 2018 – May 2019
University of Pennsylvania [Remote] – Philadelphia, PA, United States / Beijing, China <i>GRASP Lab. Advised by Prof. Jianbo Shi.</i> • Topic: Deep learning for 3D vision & generative modeling [2]	Jul 2018 – Feb 2019
Tsinghua University – Beijing, China <i>Intelligent Vision Group (IVG). Advised by Prof. Jiwen Lu.</i> • Topic: Deep learning for 3D vision & generative modeling [1]	Sep 2017 – Sep 2018
Sensetime – Beijing, China <i>[Research Intern] Group "Video Intelligence" (camera department).</i> • Major developer of a complete online real-time system for face identification in the wild (already been applied to market products). This involves video object detection, visual tracking, and face analysis.	Jun 2017 – Mar 2018

PUBLICATIONS & HONORS

[Selected Projects]: Please refer to <https://b1ueber2y.me/academic.html> for details.

[Publications]: (* indicates equal contribution) [\[GitHub\]](#) [\[Google Scholar\]](#)

- [15] Yifan Yu, **Shaohui Liu**, Rémi Pautrat, Marc Pollefeys, Viktor Larsson, "[Relative Pose Estimation through Affine Corrections of Monocular Depth Priors](#)". In CVPR 2025 (Highlight).
- [14] Siyan Dong*, Shuzhe Wang*, **Shaohui Liu**, Lulu Cai, Qingnan Fan, Juho Kannala, Yanchao Yang, "[Reloc3r: Large-Scale Training of Relative Camera Pose Regression for Generalizable, Fast, and Accurate Visual Localization](#)". In CVPR, 2025.
- [13] **Shaohui Liu***, Yidan Gao*, Tianyi Zhang*, Rémi Pautrat, Johannes Schönberger, Viktor Larsson, Marc Pollefeys, "[Robust Incremental Structure-from-Motion with Hybrid Features](#)". In ECCV, 2024.
- [12] Lei Li, Songyou Peng, Zehao Yu, **Shaohui Liu**, Rémi Pautrat, Xiaochuan Yin, Marc Pollefeys, "[3D Neural Edge Reconstruction](#)". In CVPR, 2024.
- [11] Petr Hruby, **Shaohui Liu**, Rémi Pautrat, Marc Pollefeys, Daniel Barath, "[Handbook on Leveraging Lines for Two-View Relative Pose Estimation](#)". In 3DV, 2024 (Spotlight).
- [10] Rémi Pautrat, **Shaohui Liu**, Petr Hruby, Marc Pollefeys, Daniel Barath, "[Vanishing Point Estimation in Uncalibrated Images with Prior Gravity Direction](#)". In ICCV, 2023.
- [9] **Shaohui Liu**, Yifan Yu, Rémi Pautrat, Marc Pollefeys, Viktor Larsson, "[3D Line Mapping Revisited](#)". In CVPR, 2023 (Highlight).
- [8] Wang Zhao, **Shaohui Liu**, Hengkai Guo, Wenping Wang, Yong-Jin Liu, "[PartcileSfM: Exploiting Dense Point Trajectories for Localizing Moving Cameras in the Wild](#)". In ECCV, 2022.
- [7] Wang Zhao*, **Shaohui Liu***, Yi Wei, Hengkai Guo, Yong-Jin Liu, "[A Confidence-based Iterative Solver of Depths and Surface Normals for Deep Multi-view Stereo](#)". In ICCV, 2021.
- [6] Yi Wei, **Shaohui Liu**, Yongming Rao, Wang Zhao, Jiwen Lu, and Jie Zhou, "[NerfingMVS: Guided Optimization of Neural Radiance Fields for Indoor Multi-view Stereo](#)". In ICCV, 2021 (Oral).
- [5] **Shaohui Liu**, Yinda Zhang, Songyou Peng, Boxin Shi, Marc Pollefeys and Zhaopeng Cui, "[DIST: Rendering Deep Implicit Signed Distance Function with Differentiable Sphere Tracing](#)". In CVPR, 2020.
- [4] Wang Zhao, **Shaohui Liu**, Yezhi Shu and Yong-Jin Liu, "[Towards Better Generalization: Joint Depth-Pose Learning without PoseNet](#)". In CVPR, 2020.
- [3] Ze Yang*, **Shaohui Liu***, Han Hu, Liwei Wang and Stephen Lin, "[RepPoints: Point Set Representation for Object Detection](#)", In ICCV, 2019.
- [2] **Shaohui Liu***, Xiao Zhang*, Jianqiao Wangni and Jianbo Shi, "[Normalized Diversification](#)", In CVPR, 2019.
- [1] Yi Wei*, **Shaohui Liu***, Wang Zhao*, Jiwen Lu and Jie Zhou, "[Conditional Single-view Shape Generation for Multi-view Stereo Reconstruction](#)", In CVPR, 2019.

· **Open-sourcing - Active maintainer/contributor of the following libraries:**

- [colmap](#) – the most popular structure-from-motion software.
- [limap](#) – mapping and localization support for lines and structural image features.
- [particle-sfm](#) – global structure-from-motion support for dense optical flow correspondences.
- [pyceres](#) – Python binding support for non-linear optimization.
- [PoseLib](#) – A collection of minimal solvers for camera pose estimation.

- **Honors:**
- Outstanding reviewer (ECCV 2022)
 - Direct Doctorate Scholarship (2020)
 - Qualcomm Scholarship (2017)
 - Sensetime Undergraduate Scholarship (2017)

TECHNICAL SKILLS

Programming: C/C++, CUDA, Python, MATLAB, R, HTML/CSS, JavaScript, SQL, Verilog, L^AT_EX, Linux/Unix
Language: Mandarin (native), English (fluent)